

Gear Verification

Sample document with complete example values. It shows the report the purchased export produces for YOUR input - it is not itself a report for any part.

Project: Sample project

Part/Position: no real part

Prepared by: Sample, not released

Spur gear pair: geometry and load capacity quick check

Overall assessment: OK

Inputs

Normal module m_n	3 mm
Number of teeth z_1 / z_2	20 / 60
Profile shift x_1 / x_2	0 / 0
Helix angle β	0 °
Face width b	40 mm
Load	$P = 7.5 \text{ kW}$
Pinion speed n_1	$1,450 \text{ min}^{-1}$
Application factor K_A	1.25
Gear quality	7-8
Material, gear 1	16MnCr5 / 18CrNiMo7-6
Material, gear 2	16MnCr5 / 18CrNiMo7-6
Minimum safety factors SF_{min} / SH_{min}	1.5 / 1.2

Geometry per gear

Quantity	Gear 1	Gear 2
Pitch diameter d in mm	60	180
Base diameter d_b in mm	56.3816	169.1447
Tip diameter d_a in mm	66	186
Root diameter d_f in mm	52.5	172.5
Working pitch diameter d_w in mm	60	180
Profile shift x	0	0
Equivalent number of teeth z_n	20	60
Tip tooth thickness s_{an} in mm	2.085	2.357
Minimum profile shift x_{min}	-0.1698	-2.5093
Root form circle d_{Ff} in mm	56.4602	174.7793
Root usable circle d_{Nf} in mm	56.5784	175.7624
Radial reserve $(d_{Nf} - d_{Ff})/2$ in μm	59.1	491.6
Reserve Δ_ξ along the line of action in mm	0.8681	1.8771

Gear pair

Operating center distance a	120 mm
Reference center distance a_d	120 mm
Transverse module m_t	3 mm
Operating pressure angle α_{wt}	20 °
Transverse contact ratio ϵ_α	1.6708
Overlap ratio ϵ_β	0
Total contact ratio ϵ_y	1.6708
Gear ratio i	3
Tip clearance c	0.75 mm
Tip shortening factor k (info)	0
Limiting number of teeth z_g	17.1

Tooth forces and load factors

Pinion torque T1	49.39 Nm
Tangential force Ft	1,646.4 N
Radial force Fr	599.3 N
Axial force Fa	0 N
Pitch line velocity v	4.56 m/s
Factors KA / KV / KH _β / KF _β	1.25 / 1.2 / 1.5 / 1.25

Tooth root load capacity

Quantity	Gear 1	Gear 2
Tooth form factor YFa	2.8	2.2863
Stress correction factor YSa	1.5525	1.7286
Contact ratio factor Y _ε	0.6989	0.6989
Helix angle factor Y _β	1	1
σ _{F0} in N/mm ²	41.68	37.9
σ _F in N/mm ²	78.16	71.05
σ _{Flim} in N/mm ²	430	430
Safety factor SF	11	12.1

Flank load capacity

Zone factor ZH	2.4946
Elasticity factor ZE	189.8 √(N/mm ²)
Contact ratio factor Z _ε	0.8811
Helix angle factor Z _β	1
σ _{H0}	399.02 N/mm ²
σ _H	598.54 N/mm ²
Safety factor SH (min)	2.46

Assessment criteria

Criterion	Value	Limit	Status
Transverse contact ratio ε _α	1.6708	≥ 1.1	● OK
Root interference, gear 1 (Δ _ξ ≥ g _{min})	0.8681 mm	0.06 mm	● OK
Root interference, gear 2 (Δ _ξ ≥ g _{min})	1.8771 mm	0.06 mm	● OK
Undercut, gear 1 (x ≥ x _{min})	0	-	● OK
Pointed tip limit, gear 1 (s _{an} ≥ 0.2 mn)	2.085 mm	0.6 mm	● OK
Undercut, gear 2 (x ≥ x _{min})	0	-	● OK
Pointed tip limit, gear 2 (s _{an} ≥ 0.2 mn)	2.357 mm	0.6 mm	● OK
Tooth root safety factor SF, gear 1	11	1.5	● OK
Tooth root safety factor SF, gear 2	12.1	1.5	● OK
Flank safety factor SH, gear 1	2.46	1.2	● OK
Flank safety factor SH, gear 2	2.46	1.2	● OK

Calculation basis

Gear geometry of the involute gearing with reference profile per DIN 867 (tip circles unshortened, tip shortening factor shown for reference only). The load capacity quick check follows DIN 3990 and ISO 6336: tooth root stress with load application at the tooth tip (YFa/YSa, Method C) and contact ratio factor Y_ε, flank pressure at the pitch point. Simplifications: KV taken as a flat 1.2, KH_β/KF_β from the quality table, KH_α = KF_α = 1, endurance strength without life factor, lubricant factor or size factor. The result is a reference-value check, not a complete standard verification.

Root interference (tip corner meshing): the flank is a usable involute only between the root form circle d_{Ff} and the tip circle, yet the mesh already starts at the root usable circle d_{Nf} set by the tip circle of the mating gear. Required is d_{Nf} ≥ d_{Ff} on both gears (Dubbel, G 8.1.7). The root form circle follows from the usable tool addendum hN = mn·(hfP* - ρoFP*·(1 - sin α_n)). Assessed is the reserve Δ_ξ along the line of action against g_{min} = max(0.02·mn; 0.05 mm), because the radial difference becomes insensitive near the base circle; the radial difference is reported in addition. Limits: nominal geometry without

tolerances, root side only (tip chamfers and tip relief not modelled), external gearing only, hobbing with a rack type tool without protuberance and without grinding stock only; for helical gears the transverse section approximation per ISO 21771 applies. With pronounced undercut d_{Ff} cannot be determined in closed form and the criterion counts as not verified: $\varepsilon_{\alpha, \text{nutz}}$ is then only a lower bound, so the geometric contact ratio is assessed instead and no not-OK verdict is derived from the uncertain figure. One bound still holds, because the usable involute can start no lower than the base circle: if even that upper bound of the reserve is negative, the interference is certain and is rated not OK, only its magnitude stays open. If interference occurs, SF and SH are void because they assume undisturbed involute meshing.

About this sample

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