

Spur Gear Geometry with Profile Shift

Project: _____ Part/Position: _____ Prepared by: _____

Sample document - numeric values are only included in the purchased Pro export.

Overall assessment: PASS

Inputs

Tooth counts z_1 / z_2	---
Normal module m_n	--- mm
Normal pressure angle α_n	--- °
Helix angle β	--- °
Face width b	--- mm
Specified via	---
Addendum modification k	---

Gearing geometry

Gear ratio $u = z_2/z_1$	---
Transverse module $m_t = m_n/\cos \beta$	--- mm
Transverse pressure angle α_t	--- °
Operating pressure angle α_{hawt}	--- °
Involute function $\text{inv } \alpha_{hawt}$	---

Profile shift and centre distance

Profile shift coefficient x_1	---
Profile shift coefficient x_2	---
Sum of profile shifts Σx	---
Profile shift $V_1 = x_1 \cdot m_n$	--- mm
Profile shift $V_2 = x_2 \cdot m_n$	--- mm
Reference centre distance a_d	--- mm
Operating centre distance a	--- mm
Addendum modification k	--- mm
Tip clearance c	--- mm

Gear diameters

Pitch circles d_1 / d_2	--- mm
Tip circles d_{a1} / d_{a2}	--- mm
Root circles d_{f1} / d_{f2}	--- mm
Base circles d_{b1} / d_{b2}	--- mm
Operating pitch circles d_{w1} / d_{w2}	--- mm
Normal tooth thicknesses s_{n1} / s_{n2} (pitch circle)	--- mm

Contact ratio

Transverse contact ratio ϵ_{α}	---
Overlap ratio ϵ_{β}	---
Total contact ratio ϵ_{γ}	---

Evaluation criteria

Criterion	Value	Limit	Status
Transverse contact ratio ϵ_{α} (≥ 1.25 recommended)	---	---	● PASS
Smallest margin $x - x_{\text{limit}}$ (undercut)	---	---	● PASS
Tip clearance c (basic rack profile $0.25 \cdot m_n$)	--- mm	--- mm	● PASS

Notes and calculation basis

External involute spur/helical gear pair per Roloff/Matek ch. — — — and — — —, basic rack profile DIN 867 (addendum factor 1, tip clearance factor — — —). Calculation path: transverse module and transverse pressure angle from the helix angle, operating pressure angle via the involute function $\text{inv } \alpha_{\text{hawt}} = 2 \cdot \text{Sigmax}/(z_1 + z_2) \cdot \tan \alpha_{\text{phan}} + \text{inv } \alpha_{\text{phat}}$ (inverted by Newton iteration, stopping at $1\text{e-}12$ rad) or, for a given centre distance, via $\cos \alpha_{\text{hawt}} = \cos \alpha_{\text{phat}} \cdot a_d/a$ with back-calculation of the sum of profile shifts and its split per DIN 3992, then centre distance, pitch, base, tip, root and operating pitch circles, addendum modification with tip clearance as well as transverse, overlap and total contact ratio. Not included: internal gearing (annulus), tooth thickness allowances and backlash, tip tooth thickness or pointing limit, and the load capacity per ISO 6336.

Note: The results are design and orientation aids. They do not replace independent verification, calculation and approval by a qualified person. The terms of use at maschinenbaurechner.de apply.

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